

Monotonicity Formula:

Let  $\Sigma^k \subset \mathbb{R}^n$  be an (immersed) min. submanifold,

Fix  $x_0 \in \mathbb{R}^n$  (not nec. in  $\Sigma$ ), consider  $B_r := B_r(x_0) =$  open ball of radius  $r > 0$  centered at  $x_0$

Then,  $\forall 0 < s < t < d(x_0, \partial\Sigma)$ ,

$$\frac{|\Sigma \cap B_t|}{t^k} - \frac{|\Sigma \cap B_s|}{s^k} = \int_{\Sigma \cap (B_t \setminus B_s)} \frac{|(x-x_0)^n|^2}{|x-x_0|^{k+2}} \quad (\geq 0)$$

Remark: The formula holds for "singular" min. submfd (currents or varifolds) and slightly "perturbed" in the Riemannian setting.

Proof: (L. Simon "Lectures on GMT"; C.M. Ch. 3)

W.L.O.G., take  $x_0 = 0$ .

Recall:  $\delta\Sigma(X) = \int_{\Sigma} \operatorname{div}_{\Sigma} X = 0 \quad \forall$  cpt. supp. vector field  $X$  in  $\mathbb{R}^n$ .

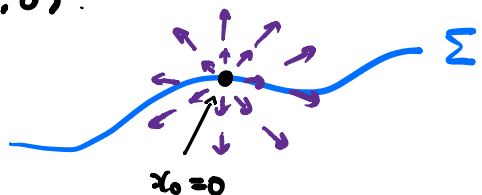
Idea: Choose  $X$  to be certain cutoff of radial vector field

*cutoff radial vec.-field*

Take  $X(x) := \gamma(r)x$  where  $r := |x| = \operatorname{dist}^{\mathbb{R}^n}(x, 0)$ .

Compute the divergence.

$$\begin{aligned} \operatorname{div}_{\Sigma} X &= \sum_{i=1}^k \nabla_{e_i}^{\mathbb{R}^n} X \cdot e_i \\ &= k \gamma(r) + \gamma'(r) \sum_{i=1}^k \underbrace{(\nabla_{e_i}^{\mathbb{R}^n} r)}_{\frac{x \cdot e_i}{r}} (x \cdot e_i) \\ &= k \gamma(r) + r \gamma'(r) \underbrace{|\nabla^T r|^2}_{= 1 - |\nabla^N r|^2} \end{aligned}$$



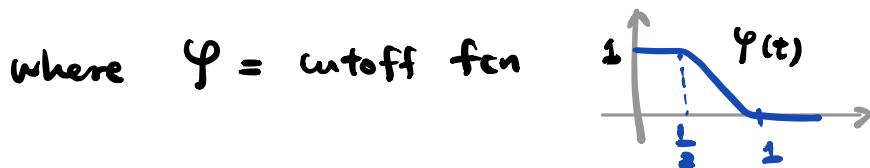
$\nabla^{\mathbb{R}^n} r = \frac{x}{r}$  ...

Integrate over  $\Sigma$ , by first variation formula,

$$0 = \int_{\Sigma} \operatorname{div}_{\Sigma} X = k \int_{\Sigma} \gamma(r) + \int_{\Sigma} r \gamma'(r) - \int_{\Sigma} r \gamma'(r) |\nabla^{\perp} r|^2$$

i.e.  $k \int_{\Sigma} \gamma(r) + \int_{\Sigma} r \gamma'(r) = \int_{\Sigma} r \gamma'(r) |\nabla^{\perp} r|^2 \dots \dots (1)$

Choose  $\gamma(r) = \varphi\left(\frac{r}{\rho}\right)$  where  $\rho > 0$  is some "parameter"



Note:  $\gamma \equiv 1$  in  $B_{\rho/2}$  and  $\gamma \equiv 0$  outside  $B_{\rho}$

Note:  $r \frac{d}{dr} \gamma(r) = -\rho \frac{d}{d\rho} \left( \varphi\left(\frac{r}{\rho}\right) \right)$  by Chain Rule

(1) becomes

$$k \int_{\Sigma} \overbrace{\varphi\left(\frac{r}{\rho}\right)}^{I(\rho)} - \rho \frac{d}{d\rho} \left( \int_{\Sigma} \overbrace{\varphi\left(\frac{r}{\rho}\right)}^{I(\rho)} \right) = -\rho \frac{d}{d\rho} \int_{\Sigma} \varphi\left(\frac{r}{\rho}\right) |\nabla^{\perp} r|^2$$

Define  $I(\rho) := \int_{\Sigma} \varphi\left(\frac{r}{\rho}\right)$ . We have

$$\begin{aligned} \frac{d}{d\rho} \left( \rho^{-k} I(\rho) \right) &= \rho^{-k} I'(\rho) - k \rho^{-k-1} I(\rho) \\ &= -\rho^{-k-1} [k I(\rho) - \rho I'(\rho)] \end{aligned}$$

"Let  $\varphi(t) \rightarrow \chi_{[0,1]}$ "

Then,  $I(\rho) = |\Sigma \cap B_{\rho}|$ .

$$\frac{d}{d\rho} \left( \rho^{-k} |\Sigma \cap B_{\rho}| \right) = \rho^{-k} \frac{d}{d\rho} \left( \int_{\Sigma \cap B_{\rho}} |\nabla^{\perp} r|^2 \right) \stackrel{\substack{\text{Coarea} \\ \downarrow \\ \text{for.}}}{=} \frac{d}{d\rho} \left( \int_{\Sigma \cap B_{\rho}} \frac{|\nabla^{\perp} r|^2}{\rho^k} \right)$$

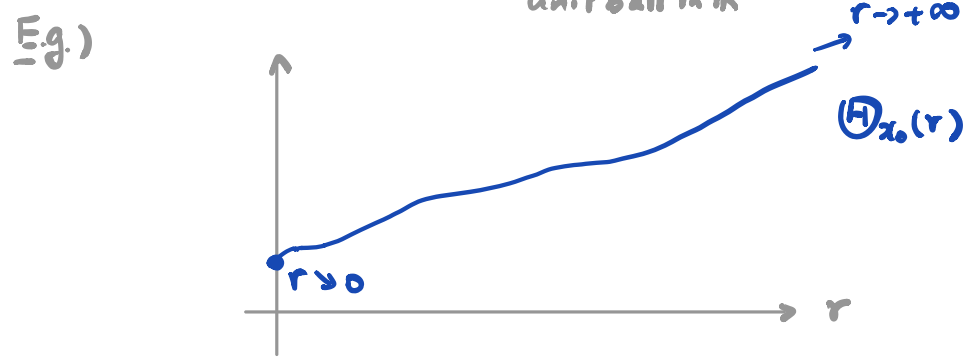
$\frac{|x^{\perp}|^2}{|x|^2}$   
 "

# Some consequences of Monotonicity Formula

(i) The "volume ratio"

$$\Theta_{x_0}(r) := \frac{|\Sigma \cap B_r(x_0)|}{\sigma_k r^k} \text{ is non-decreasing in } r.$$

$\hat{L}$  Vol. of  $k$ -dim. unit ball in  $\mathbb{R}^k$



(ii) The limits on both sides exist (even maybe  $+\infty$ )

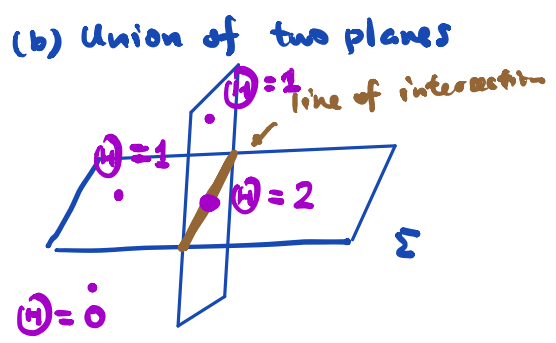
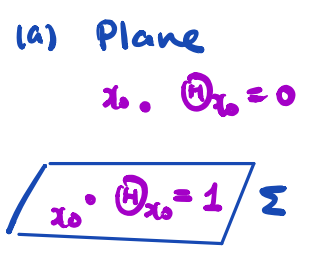
$$\Theta_{x_0} := \lim_{r \searrow 0} \Theta_{x_0}(r) < +\infty \quad \leftarrow \text{density of } \Sigma \text{ at } x_0$$

$$\Theta_{\Sigma}^{\infty} := \lim_{r \nearrow +\infty} \Theta_{x_0}(r) \leq +\infty \quad \leftarrow \text{density of } \Sigma \text{ at } \infty$$

[Note:  $\Theta_{\Sigma}^{\infty} < +\infty \iff \Sigma$  has Euclidean volume growth]

(iii) The density function  $x_0 \mapsto \Theta_{x_0}$  is upper semi-continuous.

## Examples / Pictures:



### Remarks:

- $\Theta_{x_0} = 1$  at any "regular" embedded pt. on  $\Sigma$
- $\Theta$  plays a main role in the regularity theory

# Existence Theory for Minimal Surfaces

Q: How to construct minimal surfaces in  $\mathbb{R}^n$  or  $(M^n, g)$ ?

First, look at  $\mathbb{R}^n$ , even  $n=3$  .....

Recall: max. principle  $\Rightarrow \nexists$  closed (cpt w/o bdy) min. submfd in  $\mathbb{R}^n$

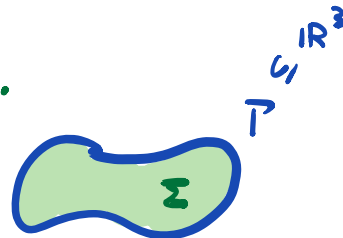
So, we are interested in:

- Global  $\checkmark$
- (1) complete, non-cpt min. surfaces (E.g. plane, catenoid, helicoid)
- Local  $\checkmark$
- (2) min. surfaces with boundary (E.g. disk)

## Plateau's Problem ("Dirichlet BVP for min. surfaces")

Given a simple closed (Jordan) curve  $\Gamma \subseteq \mathbb{R}^3$ .

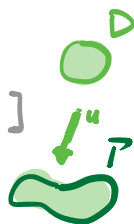
- $\exists$  min. surface  $\Sigma \subseteq \mathbb{R}^3$  with  $\partial\Sigma = \Gamma$ ?
- Is there an "area-minimizing"  $\Sigma$ ?



Subtlety: Depends very much on what "surfaces" are and how to measure their "area"?

## Various approaches to Plateau's Problem

- (1) PDE approach [  $\Gamma, \Sigma$  graphs  $\rightarrow$  Dirichlet BVP for (MSE) ]
- \* (2) \* "Parametrized" approach [ Mapping problem:  $u: D \rightarrow \mathbb{R}^3$ , energy ]
- \* (3) \* GMT approach [ weak surfaces e.g. "currents"/"varifolds" ]
- (4) "Set-theoretic" approach [ min. among "sets", Reifenberg '60s ]
- (5) "Capillary model" for min. surfaces [ F. Maggi et al. ~ 2019-20 ]



# Douglas-Rado Theorem: (Ref: C.M. ch. 4)

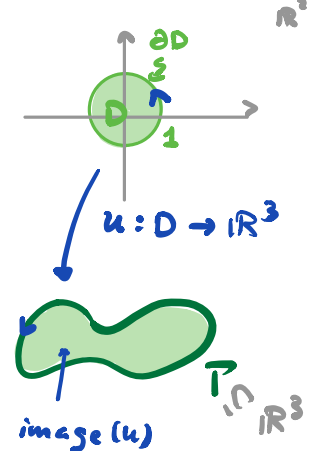
For any given piecewise  $C^1$  Jordan curve  $\Gamma \subseteq \mathbb{R}^3$ ,

$\exists$  a map  $u: D \subseteq \mathbb{R}^2 \rightarrow \mathbb{R}^3$  s.t.

(1)  $u: \partial D \rightarrow \Gamma$  is monotone & onto.

(2)  $u \in C^0(\bar{D}) \cap W^{1,2}(D)$  and  $u \in C^\infty(D)$

\* (3) "image(u)" minimizes "area" among all parametrized disk w/ boundary  $\Gamma$ .



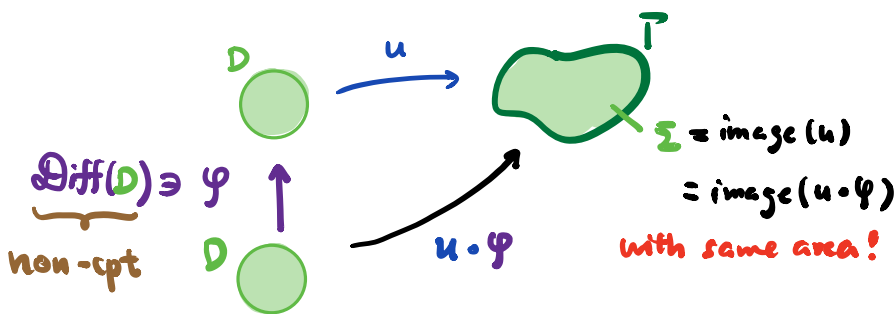
Remark: C. Morrey works in Riemannian manifold.

Q: Why is it difficult to prove a theorem like this?

Direct Method: Take a "minimizing seq." & pass to a sub-seq. limit

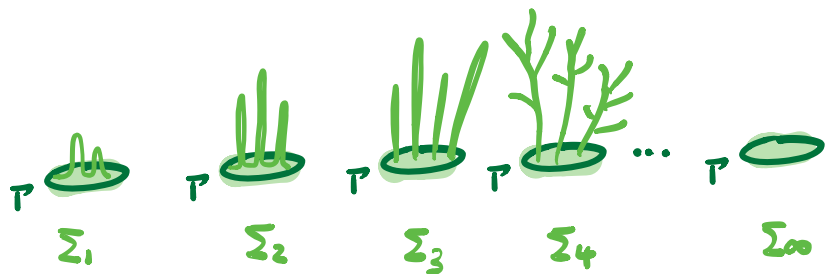
## Difficulty 1

(Area is a "geometric" notion.)



**NO compactness!**

## Difficulty 2



$\text{area}(\Sigma_i) \rightarrow \text{area}(\Sigma_\infty)$

**BUT**  $\Sigma_i \not\rightarrow \Sigma_\infty$  (in  $C^0$ -sense)

Key Idea: Work with "energy" instead of "area".

Denote:  $X_T := \{ u: D \rightarrow \mathbb{R}^3 \text{ satisfy (1), (2) in Douglas-Rado Thm} \}$

For each  $u \in X_T = \{ \text{parametrized disk w. bdy } T \}$ , define:

$$\text{Area}(u) := \int_D \sqrt{|u_x|^2 |u_y|^2 - \langle u_x, u_y \rangle^2} \, dx dy$$

Observation

← diffeomorphism invariant

$$\text{Energy}(u) := \frac{1}{2} \int_D |\nabla u|^2 \, dx dy$$

← conformally invariant

Let  $A_T := \inf_{u \in X_T} \text{Area}(u)$  &  $E_T := \inf_{u \in X_T} \text{Energy}(u)$ .

Lemma:  $A_T = E_T$ .

"Proof": We have the pointwise inequality:  $\lrcorner$  (#)

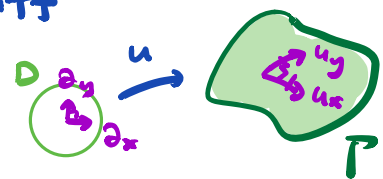
$$\left[ \sqrt{|u_x|^2 |u_y|^2 - \langle u_x, u_y \rangle^2} \leq |u_x| |u_y| \leq \frac{1}{2} (|u_x|^2 + |u_y|^2) = \frac{1}{2} |\nabla u|^2 \right]$$

Integrate over  $D$ , we get  $\text{Area}(u) \leq \text{Energy}(u) \quad \forall u \in X_T$ .

This implies  $A_T \leq E_T$ .

For  $A_T \geq E_T$ , we observe "=" holds in (#) iff

$$\langle u_x, u_y \rangle = 0 \quad \& \quad |u_x| = |u_y|$$



i.e.  $u$  is "conformal".

By the existence of (global) isothermal coordinates on  $(D, u^*g_T)$

$\Rightarrow A_T \geq E_T$ .

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